

Stable forbidden subgraphs - what is behind?

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- ▶ An open problem

■

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Multigraph: multiple edges allowed



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\mathcal{X} - a family of graphs – G is \mathcal{X} -free: does not contain a copy of any graph from \mathcal{X} as an induced subgraph

If $\mathcal{X} = \{X_1, \dots, X_k\}$: also $X_1 \dots X_k$ -free

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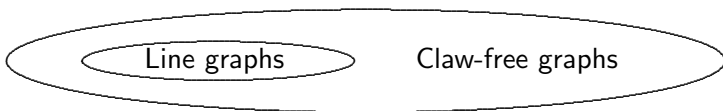
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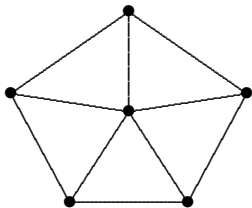
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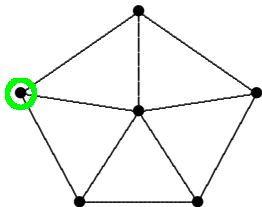
G claw-free

A vertex $x \in V(G)$ is *locally connected* if its neighborhood $N_G(x)$ induces in G a connected graph.



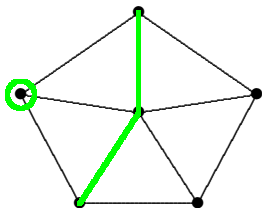
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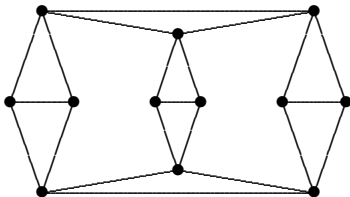
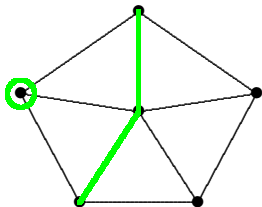
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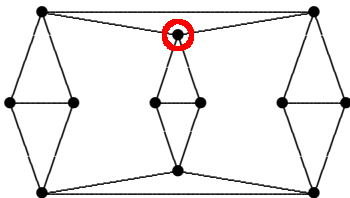
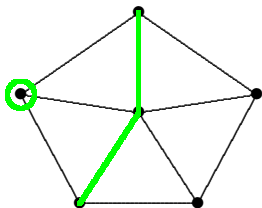
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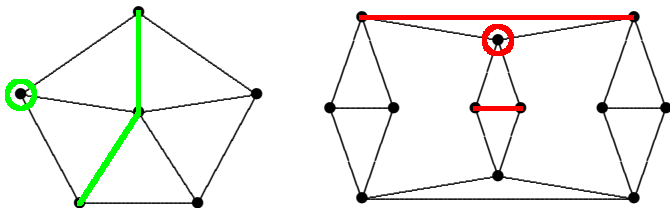
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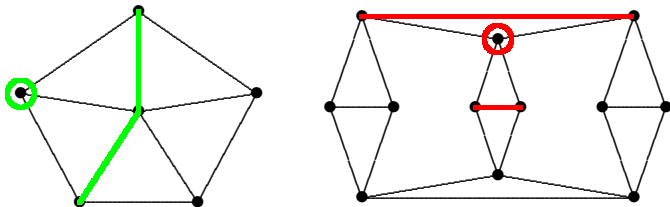
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A locally connected vertex with noncomplete neighborhood is called *eligible*.

Let $x \in V(G)$ be an eligible vertex.

The *local completion* of a graph G at x : the graph G_x^* with

$$V(G_x^*) = V(G),$$

$$E(G_x^*) = E(G) \cup \{xy \mid x, y \in N(x)\}$$

"add to the neighborhood of x all missing edges"

Let $x \in V(G)$ be an eligible vertex.

The *local completion* of a graph G at x : the graph G_x^* with

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"add to the neighborhood of x all missing edges"

$c(G)$: the *circumference* of G (the length of a longest cycle in G)

Theorem [ZR 1997]. *Let x be an eligible vertex of a claw-free graph G and let G_x^* be the local completion of G at x . Then*

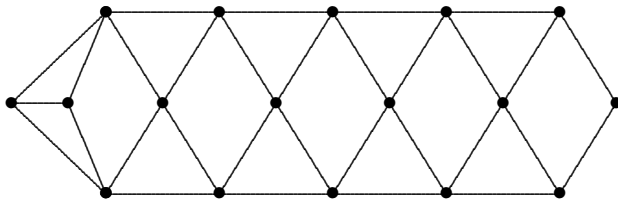
(i) G_x^* is claw-free,

(ii) $c(G_x^*) = c(G)$.

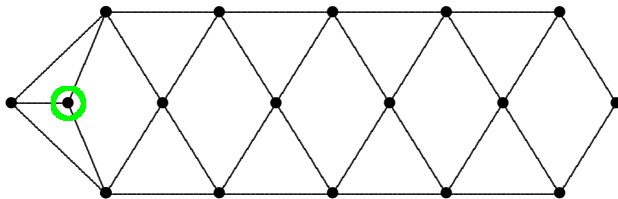
Corollary. G_x^* is hamiltonian if and only if G is hamiltonian.

The *closure of G* : the (?) graph $\text{cl}(G)$ obtained from G by recursively performing the local completion operation at eligible vertices, as long as this is possible.

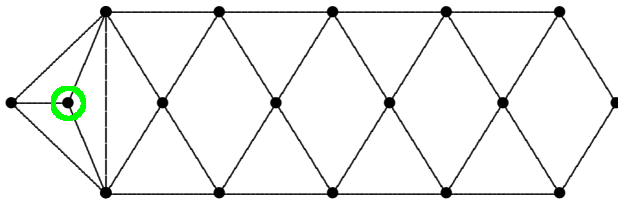
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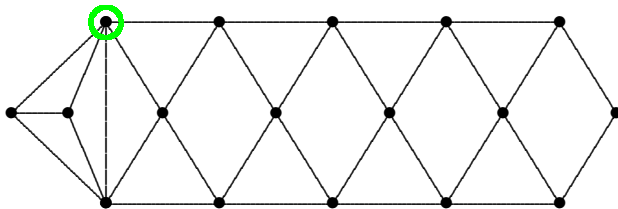
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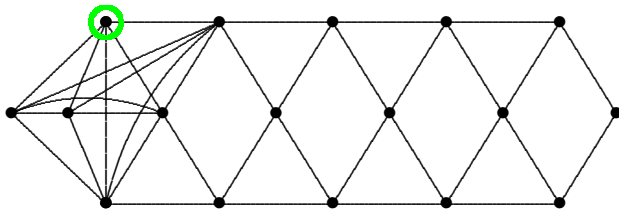
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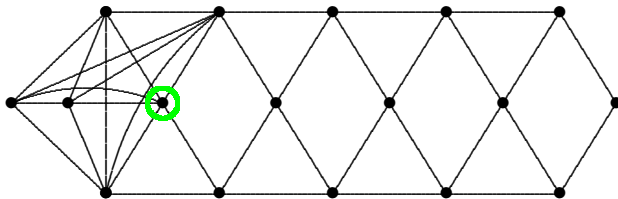
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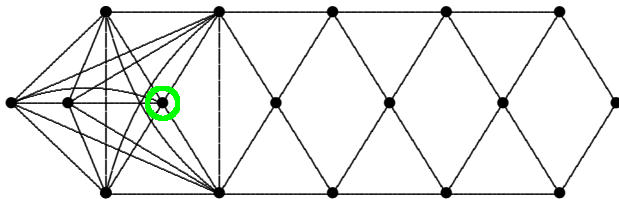
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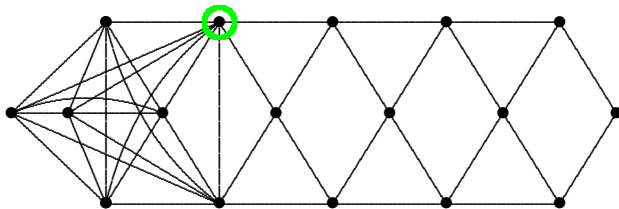
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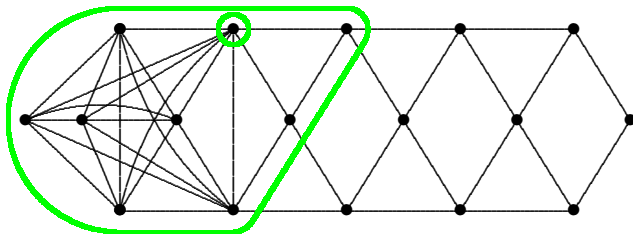
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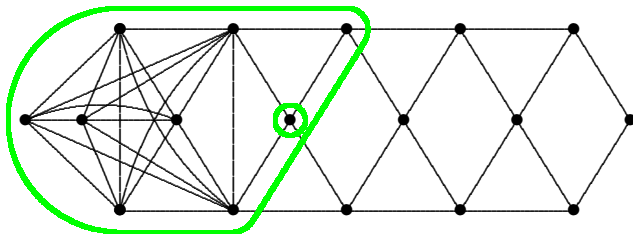
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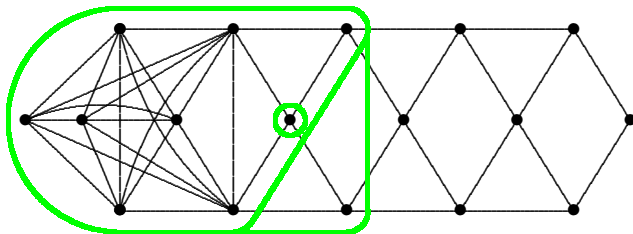
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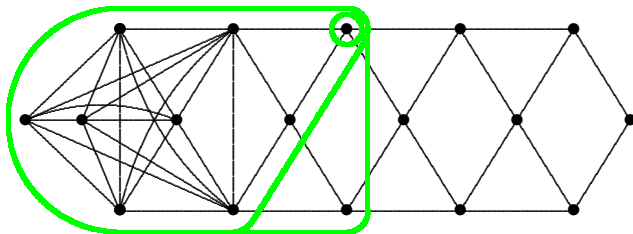
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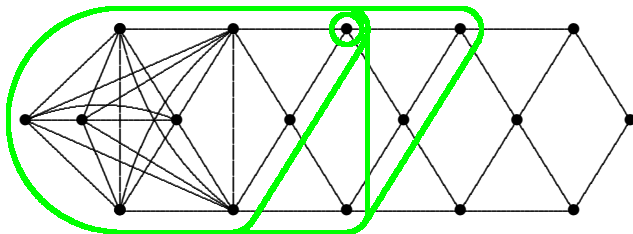
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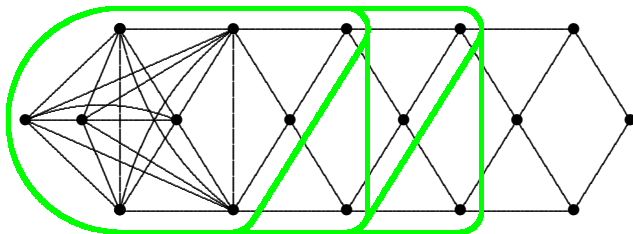
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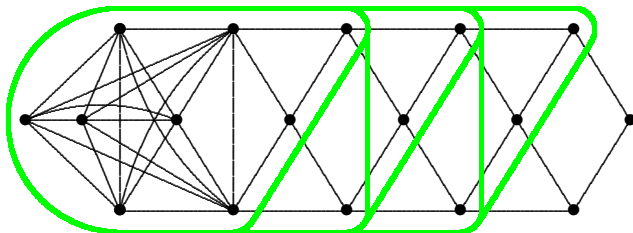
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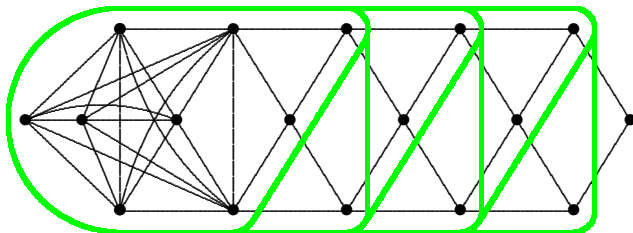
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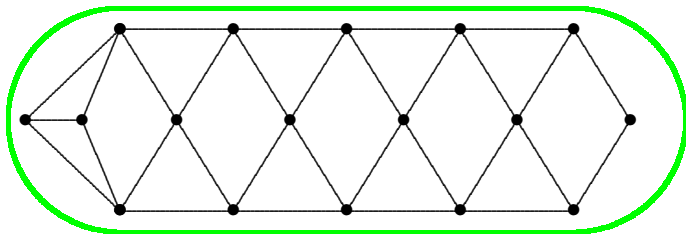
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$\text{cl}(G)$ is complete

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Theorem [ZR 1997]. *Let G be a claw-free graph. Then*

- (i) $cl(G)$ is uniquely determined,*
- (ii) $c(cl(G)) = c(G)$,*
- (iii) $cl(G)$ is the line graph of a triangle-free graph.*

Corollary. *G is hamiltonian if and only if $cl(G)$ is hamiltonian.*

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We say that

- Hamiltonicity is a *stable property*
- $c(G)$ is a *stable invariant*

in the class of claw-free graphs.

Tools:

$L(H)$: the *line graph* of a graph H

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(An eulerian subgraph $T \subset H$ is *dominating* if every edge of H has at least one vertex on T .)

■

Property / invariant	Stable	Connectivity
Circumference	YES	1
Hamiltonicity	YES	1
Having a 2-factor with $\leq k$ components	YES	1
Minimum number of components in a 2-factor	YES	1
Having a cycle cover with $\leq k$ cycles	YES	1
Minimum number of cycles in a cycle cover	YES	1
(Vertex) pancyclicity	NO	any $\kappa \geq 2$
(Full) cycle extendability	NO	any $\kappa \geq 2$
Length of a longest path	YES	1
Traceability	YES	1
Having a path factor with $\leq k$ components	YES	1 [Ishizuka]
Minimum number of components in a path factor	YES	1 [Ishizuka]
Having a path cover with $\leq k$ paths	YES	1 [Ishizuka]
Minimum number of paths in a path cover	YES	1 [Ishizuka]
Hamilton-connectedness	NO	3
	???	$4 \leq \kappa \leq 5$
	YES	6

Property / invariant	Stable	Connectivity
Homogeneous traceability	NO ??? YES	3 $4 \leq \kappa \leq 5$ 6
Having a P_3 -factor	NO YES	1 2 [Kaneko et al.]
Flower property	YES	1
Hamiltonian index	YES	1
2-factor index	YES	1 [Xiong, Saito]
Minimum number of components in a 2-factor in k -th iterated line graph	YES	1 [Xiong, Saito]
Supereulerian index	YES	1 [Xiong, Li]
Having a spanning trail with one prescribed endvertex	YES	1 [Xiong, Fu]
Having hamiltonian prism	YES	1 [Čada]
Tutte orientability	YES	1, $\delta \geq 7$ [Kriesell]

Forbidden subgraphs for hamiltonicity

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G 2-connected and XY -free $\Rightarrow G$ is hamiltonian

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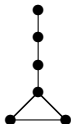
G 2-connected and XY -free $\Rightarrow G$ is hamiltonian

Theorem [Bedrossian 1991; Faudree, Gould 1997].

Let X, Y be connected graphs with $X, Y \not\cong P_3$ and let G be a 2-connected graph of order $n \geq 10$ that is not a cycle. Then, G being XY -free implies G is hamiltonian if and only if (up to a symmetry) $X = C$ and Y is an induced subgraph of some of the graphs $P_6, Z_3, B_{1,2}$ or $N_{1,1,1}$.



P_6

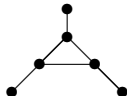


Z_3



$B_{1,2}$

*The wounded
(generalized bull)*



$N_{1,1,1}$

The net

Question: For which connected graphs Y , the class of CY -free graphs is stable?

A class of graphs \mathcal{C} is *stable under cl* if, for any $x \in V(G)$,
 $G \in \mathcal{C} \Rightarrow G_x^* \in \mathcal{C}$.

Example



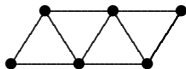
The hourglass H

Example



The hourglass H

G



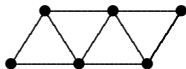
G is (C, H) -free

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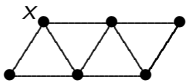


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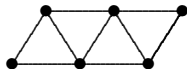


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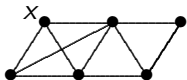
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G_x^*

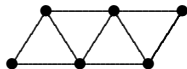


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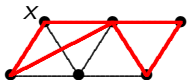
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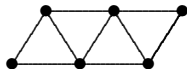
G_x^* is not (C, H) -free

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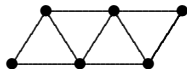
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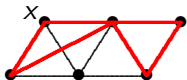
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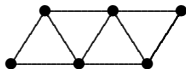
BUT: $\text{cl}(G)$ is complete $\Rightarrow \text{cl}(G)$ is (C, H) -free

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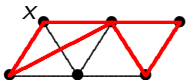
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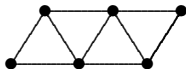
A class of graphs \mathcal{C} is *weakly stable under cl* if $G \in \mathcal{C} \Rightarrow \text{cl}(G) \in \mathcal{C}$.

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A class of graphs \mathcal{C} is *weakly stable under cl* if $G \in \mathcal{C} \Rightarrow \text{cl}(G) \in \mathcal{C}$.

Can be proved: the class of (C, H) -free graphs is weakly stable.

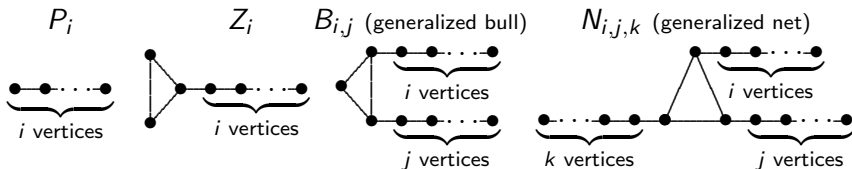
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Theorem [Brousek, Favaron, ZR, Schiermeyer 1999].

Let Y be a closed connected claw-free graph. Then the class of CY -free graphs is weakly stable if and only if

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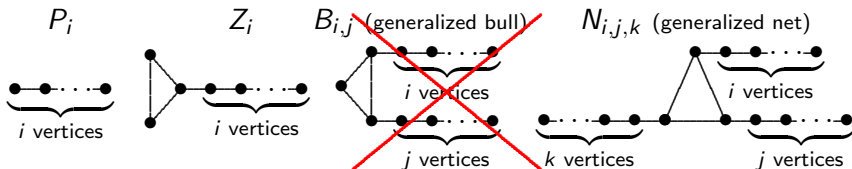


Question: For which connected graphs Y , the class of CY -free graphs is weakly stable?

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Forbidden subgraphs for hamiltonicity:

$$X = C, \quad Y \in \{P_6, Z_3, B_{1,2}, N_{1,1,1}\}.$$

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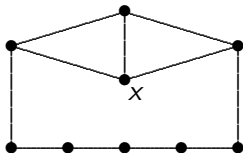
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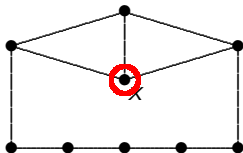
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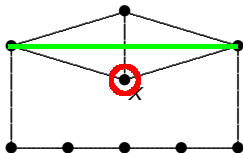
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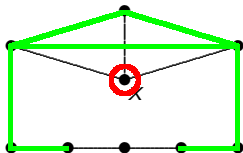
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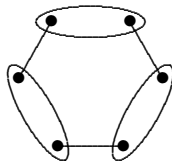
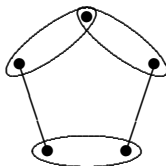
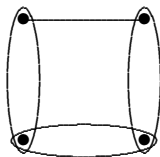
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Cycle closure

G closed, $H = L^{-1}(G)$, $C_k \subset G$ induced, $4 \leq k \leq 6$.

C_k is *eligible*:

In G :



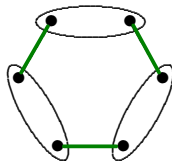
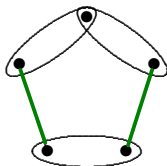
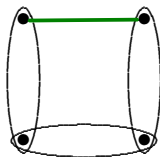
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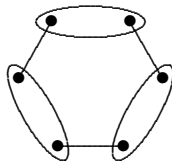
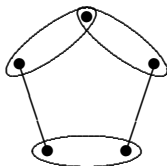
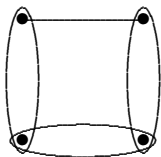
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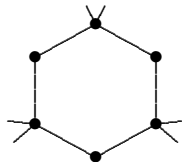
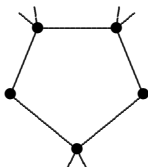
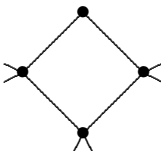
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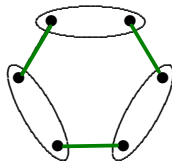
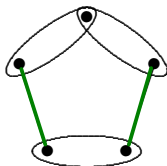
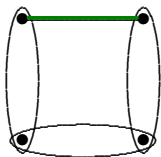
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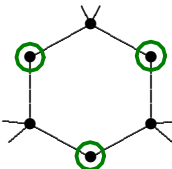
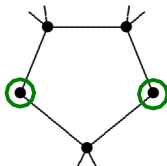
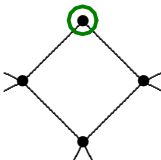
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The *cycle closure* $\text{cl}_C(G)$ of G : repeat

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Theorem [Broersma, ZR 2001]. *Let G be a claw-free graph.*

Then

- (i) $cl_C(G)$ is well-defined,
- (ii) $c(G) = c(cl_C(G))$.

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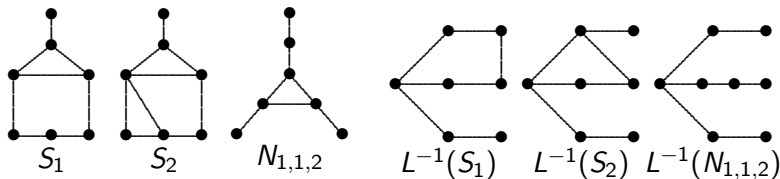
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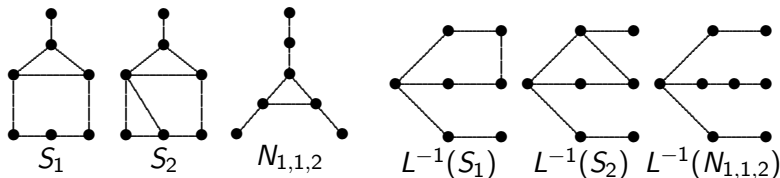
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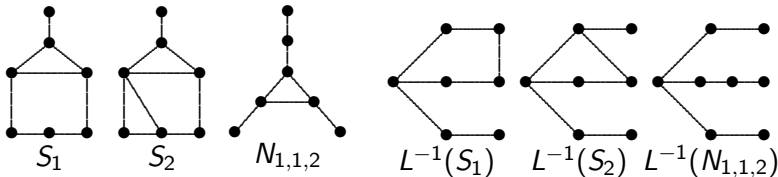
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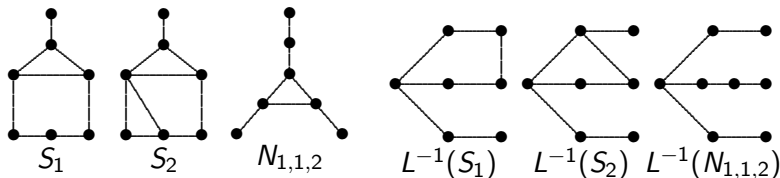
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2-factors

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Theorem [ZR, Saito, Schelp 1999].

Let G be a claw-free graph. Then $cl(G)$ has a 2-factor with at most k components if and only if G has a 2-factor with at most k components.

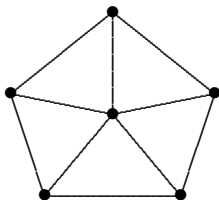
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No 2-factor with 2 components
 $cl(G)$ complete

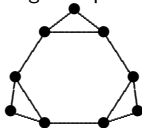
Closure for 2-factors

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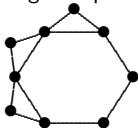
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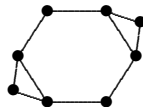
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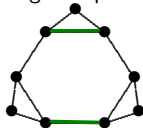


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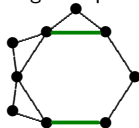
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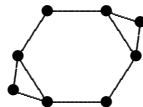
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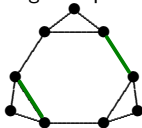


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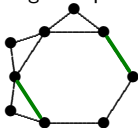
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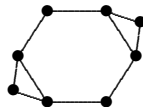
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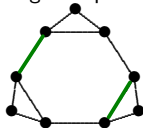


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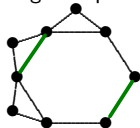
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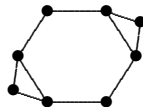
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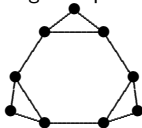


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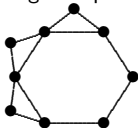
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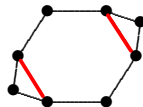
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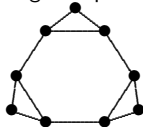


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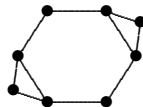
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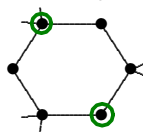


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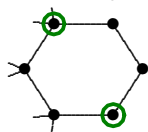


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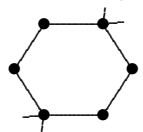
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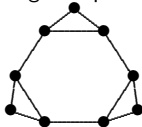


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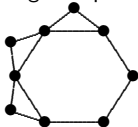
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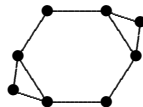
Edge-antipodal



Edge-antipodal

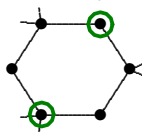


Not edge-antipodal

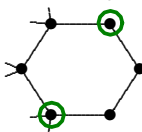


In $H = L^{-1}(G)$: C_4 , C_5 or vertex-antipodal C_6

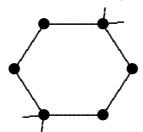
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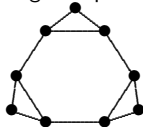


Closure for 2-factors

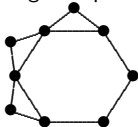
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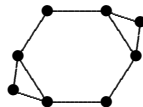
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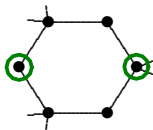


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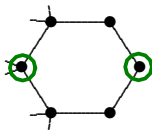


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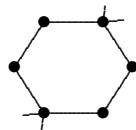
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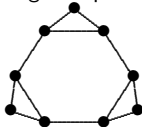


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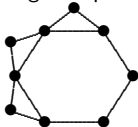
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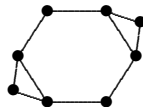
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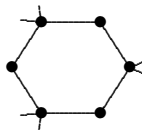


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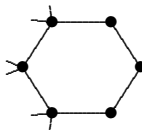


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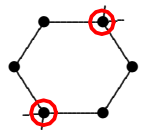
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A vertex $x \in V(G)$ is *2f-eligible* if

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2-factor-closure $cl^{2f}(G)$ of G : repeat local completions at 2f-eligible vertices as long as this is possible.

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Theorem [ZR, Xiong, Yoshimoto 2010].

Let G be a claw-free graph. Then

- (i) *the closure $cl^{2f}(G)$ is uniquely determined,*
- (ii) *there is a graph H such that*
 - (α) $L(H) = cl^{2f}(G)$,
 - (β) $g(H) \geq 6$,
 - (γ) H *does not contain any VA-cycle of length 6,*
- (iii) *G has a 2-factor if and only if $cl^{2f}(G)$ has a 2-factor.*

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Note: $cl^{2f}(G)$ does not preserve

- (non)-hamiltonicity
- minimum number of components of a 2-factor

Application: forbidden subgraphs for 2-factors

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Theorem [Faudree, Faudree, ZR 2008].

Let X and Y be connected graphs with $X, Y \not\cong P_3$, and let G be a 2-connected graph of order $n \geq 10$. Then, G being XY -free implies that G has a 2-factor if and only if, up to the order of the pairs, either

- (i) $\{X, Y\} = \{K_{1,4}, P_4\}$, or*
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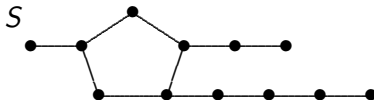
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Crucial part:

If G is 2-connected and $CB_{1,4}$ -free, then $c\ell^2(G)$ is $N_{1,1,3}$ -free.

Idea of proof:

Good sun: contains an $L^{-1}(B_{1,4})$
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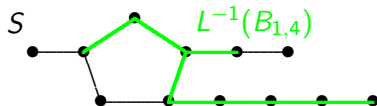


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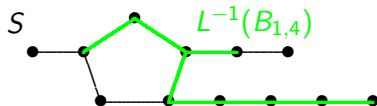


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Claims:

- (i) If G_x^* contains $L(S)$ for some good sun S , then so does G (i.e., the $CL(S)$ -free class is stable).
- (ii) The line graph of every good sun contains an induced $B_{1,4}$.
- (iii) If $cl^{2f}(G)$ contains $N_{1,1,3}$, then $cl^{2f}(G)$ contains $L(S)$ for some good sun S .

.

More closures:

- ▶ Cycle closure (for hamiltonicity, closes *some* cycles C_4 , C_5 , C_6)
- ▶ Contraction closure (for hamiltonicity, generalizes the Catlin's collapsibility technique)
- ▶ Multigraph closure (for Hamilton-connectedness, turns a claw-free graph into a line graph of a multigraph)
- ▶ Strong multigraph closure (for Hamilton-connectedness, turns a claw-free graph into a line graph of a multigraph with 'few' triangles or multiedges)
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All of them use local completions, with a different definition of eligibility.

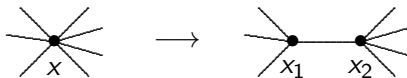
Time for generalization

.

Some definitions

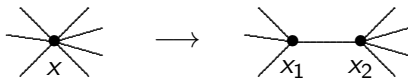
Some definitions

Splitting of type 1
of a vertex x :

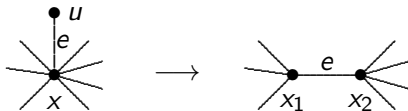


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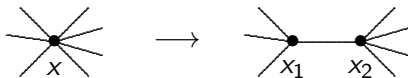


Splitting of type 2
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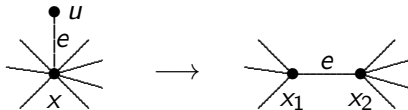


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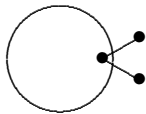
Splitting of type 1
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Splitting of type 2
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Cherry: a pair of pendant edges
with a common vertex



No cherry: *cherry-free*

Proposition 1. *Let G be a claw-free graph and $x \in V(G)$. If G_x^* contains an induced subgraph X such that $X = L(Y)$, where Y is a triangle-free and cherry-free graph, then G contains an induced subgraph X' such that $X' = L(Y')$, where either*

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$$S = E(X) \cap E(G) \quad (\text{"old edges"})$$

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It needs some work to get the following:

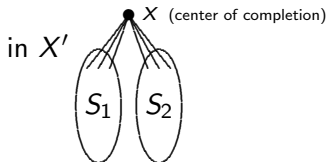
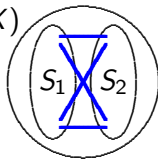
Claim. *The graph K_S satisfies one of the following:*

- (i) K_S has two components and both are cliques,*
 - (ii) K_S contains a simplicial vertex u , the graph $K_S - u$ has two complete components, and u is universal in K_S .*
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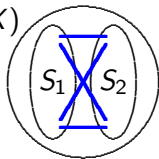
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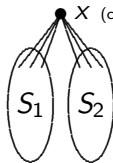
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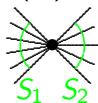
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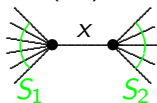
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in $Y = L^{-1}(X)$



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Vertex splitting of type 1

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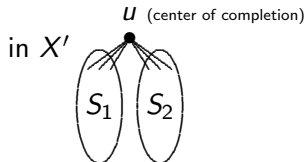
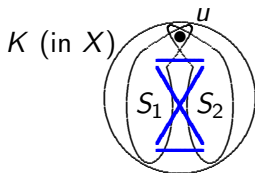
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Case (ii):

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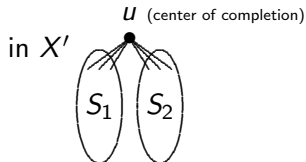
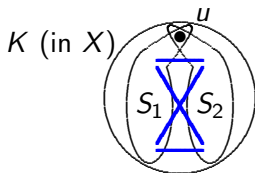
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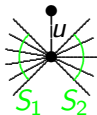
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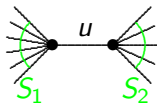
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in $Y = L^{-1}(X)$



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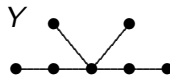
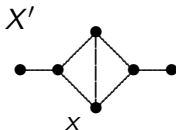
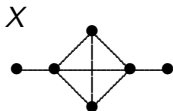


Vertex splitting of type 2

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Examples.

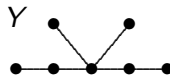
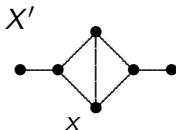
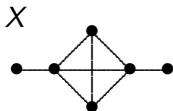
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If $X' \stackrel{\text{IND}}{\subset} G$, then $X \stackrel{\text{IND}}{\subset} G_X^*$ and $X = L(Y)$, but Y' does not exist since X' is not a line graph.

Examples.

1.

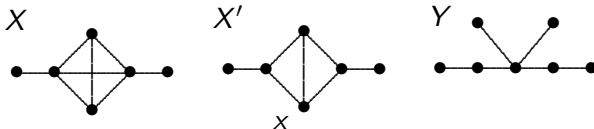


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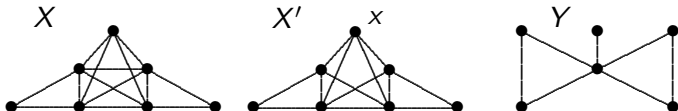
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2.



Similarly, if $X' \stackrel{\text{IND}}{\subset} G$, then $X \stackrel{\text{IND}}{\subset} G_x^*$ and $X = L(Y)$, but X' (and also $X' - x$) is not a line graph.

Hence the assumption that Y is triangle-free cannot be omitted.

A family of graphs \mathcal{Y} is *closed under vertex splitting* (or briefly *split-closed*), if, for any $Y \in \mathcal{Y}$ and any Y' obtained from Y by vertex splitting (of type 1 or 2), Y' contains a subgraph $Y'' \in \mathcal{Y}$.

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The following result characterizes families of closed forbidden subgraphs that yield stable classes.

Theorem 2. *Let \mathcal{H} be the class of all triangle-free and cherry-free graphs and let $\mathcal{Y} \subset \mathcal{H}$ and $\mathcal{X} = L(\mathcal{Y})$. Then the class $\text{Forb}(C, \mathcal{X})$ is stable if and only if \mathcal{Y} is split-closed.*

■

Examples. 1. $\text{Forb}(C, \mathcal{X})$, where
 $\mathcal{X} = \{P_i\}$ for any fixed $i \geq 2$ or
 $\mathcal{X} = \{N_{i,j,k}\}$ for any fixed $i, j, k \geq 1$

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2. The graphs S_1 , S_2 and $N_{1,1,2}$:

Splitting of any vertex in any of the graphs $L^{-1}(S_1)$, $L^{-1}(S_2)$ or $L^{-1}(N_{1,1,2})$ gives a graph containing $L^{-1}(N_{1,1,2})$, hence $\text{Forb}(C, S_1, S_2, N_{1,1,2})$ is stable.

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$\mathcal{X} = \{N_{i,j,k}\}$ for any fixed $i, j, k \geq 1$

2. The graphs S_1 , S_2 and $N_{1,1,2}$:

Splitting of any vertex in any of the graphs $L^{-1}(S_1)$, $L^{-1}(S_2)$ or $L^{-1}(N_{1,1,2})$ gives a graph containing $L^{-1}(N_{1,1,2})$, hence $\text{Forb}(C, S_1, S_2, N_{1,1,2})$ is stable.

3. $L(\mathcal{S})$, where \mathcal{S} is the family of good suns:

Splitting of any vertex in a good sun gives a good sun (this is clearly true for splitting of type 1; for splitting of type 2 needs some more work but can be done).

Hence $\text{Forb}(C, L(\mathcal{S}))$ is stable.

■

4. $\mathcal{C}_k = \{C_i\}_{i=k}^{\infty}$ – all cycles of lengths $i \geq k$ ($k \geq 3$ fixed).

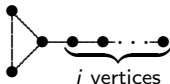
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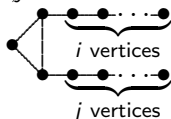
5. H (hourglass)



Z_i



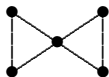
$B_{i,j}$ (generalized bull)



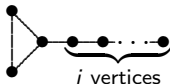
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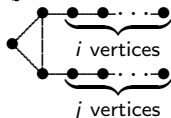
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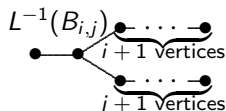
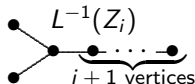
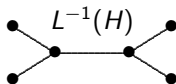
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If Y is any of the graphs $L^{-1}(H)$, $L^{-1}(Z_i)$ or $L^{-1}(B_{i,j})$,



then splitting of type 2 of a vertex of degree 3 yields a graph not containing Y as a subgraph. Hence none of the classes $\text{Forb}(C, H)$, $\text{Forb}(C, Z_i)$, $\text{Forb}(C, B_{i,j})$ is stable.

Minimal families of forbidden subgraphs

We know: $\text{Forb}(C, S_1, S_2, N_{1,1,2})$ is a stable class.

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Y is a *subdivision of a star* : Y can be obtained from a star $K_{1,r}$ by adding at least one vertex of degree 2 to each of its edges.

Special case $r = 3$: Y is a *subdivision of the claw*.

Note: Y is a subdivision of the claw $\Leftrightarrow L(Y)$ is a generalized net.

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Then some $Y_i \in \mathcal{Y}$ is a path or a subdivision of the claw.*

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Claim 1. *If \mathcal{Y} contains a graph Y with $\nu(Y) = r \geq 1$, then \mathcal{Y} contains a graph Y' with $\nu(Y') \leq r - 1$.*

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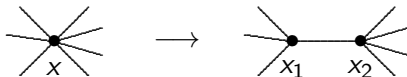
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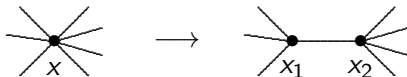
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A contradiction with the choice of T .

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From Proposition 3 immediately:

Theorem 4. *Let \mathcal{X} be a finite family of line graphs of triangle-free and cherry-free graphs such that $\text{Forb}(C, \mathcal{X})$ is stable. Then \mathcal{X} contains a path or a generalized net.*

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But: let $\mathcal{X}_k = \{C_i \mid i \geq k\}$. Then, for any $k \geq 4$, $\mathcal{X}_k \subset \mathcal{X}$, $\mathcal{X}_k \neq \mathcal{X}$, and $\text{Forb}(C, \mathcal{X}_k)$ is stable.

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Remains: $\eta(T) \leq 1$ and $|V_{\geq 4}(T)| = 0$, ie., T is a path or a subdivision of the claw.

Immediately from Proposition 5:

Theorem 6. *Let \mathcal{X} be a family of line graphs of triangle-free and cherry-free graphs such that $\text{Forb}(C, \mathcal{X})$ is stable. Then \mathcal{X} contains a subfamily $\mathcal{X}' \subset \mathcal{X}$, $\mathcal{X}' \neq \mathcal{X}$, such that $\text{Forb}(C, \mathcal{X} \setminus \mathcal{X}')$ is stable, unless $|\mathcal{X}| = 1$ and \mathcal{X} contains a path or a generalized net.*

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Unstable classes and stabilizers

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- (i) turns a claw-free graph into a line graph by a series of local completions at eligible vertices
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 - Cycle closure (for hamiltonicity)
 - Closure for 2-factor
 - Contraction closure (for hamiltonicity)
 - Multigraph closure (for Hamilton-connectedness)
 - Strong multigraph closure (for Hamilton-connectedness)
 - Closure for 1-Hamilton-connectedness

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A family \mathcal{S} of connected triangle-free and cherry-free graphs s.th.

(i) \mathcal{S} is split-closed,

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(iii) every cl -closed k -connected $(C, L(\mathcal{S}))$ -free graph is (C, \mathcal{G}) -free,

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In the special case when $\mathcal{B} = \{B\}$ and $\mathcal{G} = \{Q\}$ we simply say that \mathcal{S} is a (k, B, Q, cl) -stabilizer.

■

Theorem. *Let $k \geq 1$, let \mathcal{B}, \mathcal{G} be classes of graphs such that there is a $(k, \mathcal{B}, \mathcal{G}, \text{cl})$ -stabilizer, and let G be a k -connected (C, \mathcal{B}) -free graph. Then $\text{cl}(G)$ is (C, \mathcal{G}) -free.*

Equivalently,

$$\text{cl}(\text{Forb}_k(C, \mathcal{B})) \subset \text{Forb}_k(C, \mathcal{G}).$$

Consider again the family $\text{Forb}(C, \mathcal{S})$, where $\mathcal{S} = \{S_1, S_2, N_{1,1,2}\}$.

- $\text{Forb}(C, \mathcal{S})$ is stable,
- \mathcal{S} is not minimal stable (since $\text{Forb}(C, N_{1,1,2})$ is also stable),
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Open problem: a characterization of minimal (in some sense) stabilizers for given families \mathcal{B}, \mathcal{G} .

Thank you

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