

A Composed Confidence Measure for Automatic Face Recognition in Uncontrolled Environment

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Abstract: This paper is focused on automatic face recognition in order to annotate people in photographs taken in completely uncontrolled environment. Recognition accuracy of the current approaches is not sufficient in this case and it is thus beneficial to improve the results. We would like to solve this issue by proposing a novel confidence measure method to identify the incorrectly classified examples at the output of our classifier. The proposed approach combines two measures based on the *posterior* probability and two ones based on the *predictor* features in a supervised way. The experiments show that the proposed approach is very efficient, because it detects almost all erroneous examples.

1 INTRODUCTION

Automatic face recognition consists in the use of a computer for identification of a person from a digital photograph. This area has been focused on by many researchers and many algorithms have been proposed during the past two decades. Nowadays, face recognition can be seen as one of the most progressive biometric authentication methods and represents a key task in several commercial or law enforcement applications as for example surveillance of wanted persons, access control to restricted areas, automatic annotation of the photos used in the recently very popular photo sharing applications or in the social networks, etc.

The majority of the proposed methods achieves high recognition accuracy only in the particular conditions (sufficiently aligned faces, similar face pose and lighting conditions, etc.). Unfortunately, their recognition results are significantly worse when the above mentioned constraints are not fulfilled. Many approaches to resolve this issue have been proposed, however only few of them perform well in a fully uncontrolled environment.

In our previous work, we proposed the SIFT based Kepenekci face recognition method (Lenc and Král, 2013) and showed that it significantly outperforms other approaches particularly on the uncontrolled face images. However, its recognition accuracy is still not

perfect. Therefore, we proposed in (Lenc and Král, 2011) two Confidence Measure (CM) approaches in order to detect and handle incorrectly recognized examples. These approaches are based on the *posterior* class probability. We experimentally showed that these approaches are very promising in our task. However, it is beneficial a further improvement of the results.

The main goal of this paper thus consists in proposing a novel composed confidence measure approach which would improve the results of the methods proposed previously. This approach combines two previously proposed measures with two novel ones in a supervised way using a multi-layer perceptron classifier. The novel measures are based on the *predictor* features which characterize our face model.

The results of this work will be used by the Czech News Agency (ČTK¹) to annotate people in photographs during insertion into the photo-database².

The following section gives a brief overview of important face recognition and confidence measure approaches. Section 3 describes our face recognition method. This section also details the proposed confidence measure approach. Section 4 evaluates and compares the performance of our confidence measure on the ČTK corpus. In the last section we discuss the

¹<http://www.ctk.eu>

²<http://multimedia.ctk.cz/en/foto/>

achieved results and give some further research directions.

2 RELATED WORK

This section is composed of two parts. The successful face recognition approaches are described in the first part, while the second part is focused on the confidence measure task itself.

2.1 Face Recognition

One of the first successful approaches is Eigenfaces (Turk and Pentland, 1991). This approach is based on the Principal Component Analysis (PCA). Unfortunately, it is sensitive on variations in lighting conditions, pose and scale. However, the PCA based approaches are still popular, as shown in (Poon et al., 2011).

Another method, the Fisherfaces (Belhumeur et al., 1997), is derived from Fisher's Linear Discriminant (FLD). According to the authors, this approach should be less sensitive to changing lighting conditions than Eigenfaces.

Independent Component Analysis (ICA) can be also successfully used in the automatic face recognition field (Bartlett et al., 2002). Contrary to Eigenfaces, ICA uses higher order statistics. It thus provides more powerful data representation. The authors showed that ICA performs slightly better than PCA method on the FERET corpus.

Another efficient face recognition approach is the Elastic Bunch Graph Matching (EBGM) (Bolme, 2003). This approach uses features constructed by the Gabor wavelet transform. Several other successful approaches based on Gabor wavelets have been introduced (Shen and Bai, 2006). Some approaches (Shen, 2005) combine the pre-processing with Gabor wavelets with well-established methods such as Eigenfaces, Fisherfaces, etc.

Kepenekci proposes in (Kepenekci, 2001) an algorithm that addresses the main issue of Elastic Bunch Graph Matching, manual labelling of the landmarks. The proposed method outperforms the classical EBGM.

Recently, the Scale Invariant Feature Transform (SIFT) is successfully used for face recognition (Aly, 2006). The main advantage of this approach is the ability to detect and describe local features in images. The features are invariant to image scaling, translation and rotation. Moreover, they are also partly invariant to changes in illumination. Therefore, this approach is beneficial for face recognition in real con-

ditions where the images differ significantly. Another approach based on the SIFT, called Fixed-key-point-SIFT (FSIFT), is presented in (Krizaj et al., 2010).

For further information about the face recognition, please refer to the survey (Beham and Roomi, 2013).

2.2 Confidence Measure

Confidence measure is used as a post-processing of the recognition to determine whether the result is correct or not. The incorrectly recognized samples should be removed from the recognition set or another processing (e.g. manual correction) can be further realized.

This technique is mainly used in the automatic speech processing field (Senay et al., 2011; Wessel et al., 2001) and is mostly based on the *posterior* class probability. However, two other groups of approaches exist (Jiang, 2005). The first one uses a classifier in order to decide whether the classification is correct or not. This classifier uses a set of the so-called *predictor* features which should have a maximal discriminability between the correct and incorrect classes. The second group uses a likelihood ratio between the *null* (a correct recognition) and the *alternative* (an incorrect recognition) hypotheses.

The confidence measure can be successfully used in other research areas as shown in (Servin et al., 2010) for genome maps construction, in (Hu and Mordohai, 2012) for stereo vision or in (Marukatat et al., 2002) for handwriting sentence recognition.

Another approach related to the confidence measure is proposed by Proedrou et al. in the pattern recognition task (Proedrou et al., 2002). The authors use a classifier based on the nearest neighbours algorithm. Their confidence measure is based on the algorithmic theory of randomness and on transductive learning.

Unfortunately, only few works about the confidence measure in the face recognition domain exist. Li and Wechsler propose a face recognition system which integrates a confidence measure (Li and Wechsler, 2003) in order to reject unknown individuals or to detect incorrectly recognized faces. Their confidence measure is, as in the previous case, based on the theory of randomness. The proposed approaches are validated on the FERET database.

Eickeler et al. propose and evaluate in (Eickeler et al., 2000) five other CMs also in the face recognition task. They use a pseudo 2-D Hidden Markov Model classifier with features created by the Discrete Cosine Transform (DCT). Three proposed confidence measures are based on the *posterior* probabilities and two others on ranking of results. Authors experimen-

tally show that the *posterior* class probability gives better results for the recognition error detection task.

Note that the most of the proposed approaches are unsupervised. However, the supervised (Sukkar, 1994) and semi-supervised (Deng and Schuller, 2012) methods have been also proposed.

3 CONFIDENCE MEASURE FOR FACE RECOGNITION

3.1 Face Recognition

For the face recognition task, we use our previously proposed SIFT based Kepenekci method (Lenc and Král, 2013) which uses the efficient SIFT algorithm for parametrization and adapted Kepenekci matching (Lenc and Král, 2012) for recognition. This method was chosen, because as proven previously, it significantly outperforms other approaches particularly on lower quality real data.

3.1.1 SIFT parametrization

This algorithm creates an image pyramid with re-sampling between each level to determine potential key-point positions. Each pixel is compared with its neighbours. Neighbours in its level as well as in the two neighbouring levels are analysed. If the pixel is maximum or minimum of all neighbouring pixels, it is considered to be a potential key-point.

For the resulting set of key-points their stability is determined. The locations with low contrast and unstable locations along edges are deleted.

The orientation of each key-point is computed next. The computation is based on gradient orientations in the neighbourhood of the pixel. The values are weighted by the magnitudes of the gradient.

The last step consists in the descriptor creation. The computation involves the 16×16 neighbourhood of the pixel. Gradient magnitudes and orientations are computed in each point of the neighbourhood. Their values are weighted by a Gaussian. For each sub-region of size 4×4 (16 regions), the orientation histograms are created. Finally, a vector containing 128 (16×8) values is created.

3.1.2 Adapted Kepenekci matching

This approach combines two methods of matching and uses the weighted sum of the two results.

Let T be a test image and G a gallery image. For each feature vector t of face T we determine a set of relevant vectors g of face G . Vector g is relevant iff:

$$\sqrt{(x_t - x_g)^2 + (y_t - y_g)^2} < distanceThreshold \quad (1)$$

where x and y are the coordinates of the feature vector points.

If no relevant vector to vector t is identified, vector t is excluded from the comparison procedure. The overall similarity of two faces OS is computed as the average of similarities between each pair of corresponding vectors as:

$$OS_{T,G} = mean\{S(t,g), t \in T, g \in G\} \quad (2)$$

Then, the face with the most similar vector to each of the test face vectors is determined. The C_i value denotes how many times gallery face G_i was the closest one to some of the vectors of test face T . The similarity is computed as C_i/N_i where N_i is the total number of feature vectors in G_i . The weighted sum of these two similarities is used for similarity measure:

$$FS_{T,G} = \alpha OS_{T,G} + \beta \frac{C_G}{N_G} \quad (3)$$

The face is recognized by the following equation:

$$F\hat{S}_{T,G} = \arg \max_G (FS_{T,G}) \quad (4)$$

The cosine similarity is used for vector comparison.

3.2 Confidence Measure

3.2.1 Posterior class probability approaches

Let $P(F|C)$ be the output of the classifier, where C is the recognized face class and F represents the face features. The values $P(F|C)$ are normalized to compute the *posterior* class probabilities as follows:

$$P(C|F) = \frac{P(F|C) \cdot P(C)}{\sum_{I \in \mathcal{FIM}} P(F|I) \cdot P(I)} \quad (5)$$

\mathcal{FIM} represents the set of all individuals and $P(C)$ denotes the *prior* probability of the individual's (face) class C .

We propose two different approaches. In the first approach, called *absolute confidence value*, only faces \hat{C} complying with

$$\hat{C} = \arg \max_C (P(C|F)) \quad (6)$$

$$P(\hat{C}|F) > T \quad (7)$$

are considered as being recognized correctly.

The second approach, called *relative confidence value*, computes the difference between the *best* score and the *second best* one by the following equation:

$$P\Delta = P(\hat{C}|F) - \max_{C \neq \hat{C}}(P(C|F)) \quad (8)$$

Only the faces with $P\Delta > T$ are accepted. This approach aims to identify the “dominant” faces among all the other candidates. T is the acceptance threshold and its optimal value is adjusted experimentally.

Note that these two measures working separately were already presented in (Lenc and Král, 2011). However, their description is important in the context of the whole composed approach.

3.2.2 Predictor feature approaches

As already stated, this type of approaches uses the features with a maximal discriminability between the correct and incorrect classes to classify the recognition results. Two measures are proposed next.

The first one is based on the number of vectors in the model with the highest output value during the recognition task (i.e. the recognized face model). The number of vectors is given by the results of the SIFT algorithm. A face model with a high number of vectors is more general and it can be more likely identified as a good one. Conversely, a few vector face model is more accurate. Therefore, when this model is chosen as a good one (the highest output value) we assume that it is very probable that the recognition is correct.

Let V be the number of vectors in the face model and let T be the acceptance threshold. Only the faces where $V < T$ are accepted. The optimal value of the threshold T will be set experimentally. This measure is hereafter called the *vector number* approach.

The second measure uses a standard deviation of the similarities among images in the recognized face model. Let the recognized model M be composed of the images I_1, I_2, \dots, I_N . The S measure is defined as follows:

$$S = \sqrt{\frac{1}{N} \sum_{i=1}^N (FS_{I_i, M \setminus I_i} - \mu)^2} \quad (9)$$

where $FS_{I_i, M \setminus I_i}$ is the similarity (see Equation 3) of the image I_i and a model $M \setminus I_i$ created from the remaining images from model M and μ is computed by the following equation:

$$\mu = \frac{1}{N} \sum_{i=1}^N FS_{I_i, M \setminus I_i} \quad (10)$$

Similarly as in the case of the *vector number* measure we suppose that higher standard deviation characterizes a more general face model and vice versa.



Figure 1: Examples of one face from the ČTK face corpus

Therefore, only the recognition results where $S < T$ are accepted. The optimal value of the acceptance threshold T will be set experimentally. This measure is hereafter called the *standard deviation* approach.

3.2.3 Composed supervised approach

Let R_k be the score obtained by a partial unsupervised measure k described above and let variable H determines whether the face image is classified correctly or not. A Multi-layer Perceptron (MLP) which models the *posterior* probability $P(H|R_1, \dots, R_N)$ is used to combine all partial measures in a supervised way. Note that the variable N represents the number of measures to combine

In order to identify the best performing topology, several combinations and MLP configurations are built and evaluated. The MLP topologies will be described in detail in the experimental section.

4 EXPERIMENTS

4.1 Czech News Agency Corpus

This corpus is composed of images of individuals in an uncontrolled environment that were randomly selected from the large ČTK database. All images were taken over a long time period (20 years or more). The corpus contains grey-scale images of 638 individuals of size 128×128 pixels. It contains about 10 images for each person. The orientation, lighting conditions and image backgrounds differ significantly.

Figure 1 shows examples of one face from this corpus. This corpus is available for free for research purposes at <http://home.zcu.cz/~pkral/sw/> or upon request to the authors.

4.2 Recognition Results with Confidence Measure

Three experiments are described next. The first experiment analyses the discriminability of the proposed partial measures by histograms. This experiment is realized in order to show the suitability of the proposed measures. The second experiment reports the

results of the measures also used separately. In the last experiment, we show the classification results of the whole composed approach.

4.2.1 Discriminability of the proposed measures

In the first experiment, we would like to analyse the discriminability of the proposed partial measures. We created two histograms for every measure in order to analyse the distribution of the correctly and incorrectly classified faces. The reported output densities of the measures are based on the 638 values (the number of individuals in the corpus). Note that all output values are normalized to the interval $[0..1]$.

Figure 2 shows the output densities of the correctly and incorrectly classified faces when the *absolute confidence value* measure is used. These histograms show that the majority of the correctly recognized face examples has higher output values than the incorrectly recognized ones. This fact confirms our assumption that the first measure is suitable for our task and should be useful to be integrated to the whole composed method.

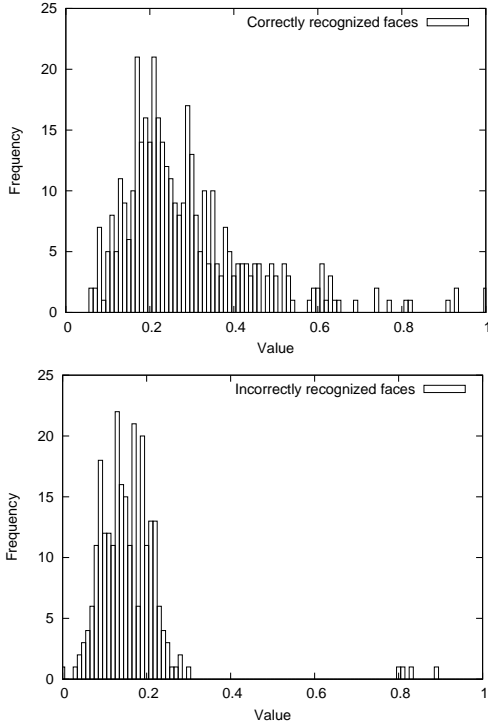


Figure 2: Histograms of the correctly (top) and incorrectly (bottom) classified faces using the *absolute confidence value* measure

Figure 3 plots the output densities when the *relative confidence value* measure is used. These histograms show clearly that the discriminability of this

measure is better than the previous one. Almost all correctly recognized face examples have higher output values than the incorrectly recognized samples. Therefore this measure should be suitable for our task and we decided to combine it with the other ones by an MLP. Moreover, we assume that this measure used separately outperforms the previously proposed one.

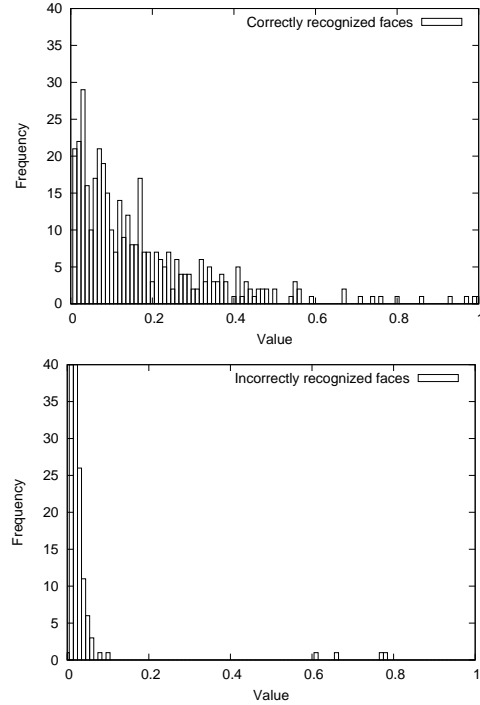


Figure 3: Histograms of the correctly (top) and incorrectly (bottom) classified faces using the *relative confidence value* measure

Figure 4 depicts the output densities when the *vector number* measure is used. These histograms show that this measure is less discriminant than the two ones presented previously. However, the correctly recognized examples have slightly inferior output values than the incorrectly ones. This fact confirms our assumption (see Sec. 3.2.2) that the confidence of a few vector model is high. We assume that this measure will bring poor results if used separately. However, it can add some further information when it will be combined with the other approaches. Therefore, we decided to integrate it into the whole composed approach.

The output densities of the last *standard deviation* measure are reported in Figure 5. The discriminability of these two histograms are limited and it is difficult to propose some conclusions about this measure. However, we decided to use this measure in the further experiments and verify its usefulness experimentally.

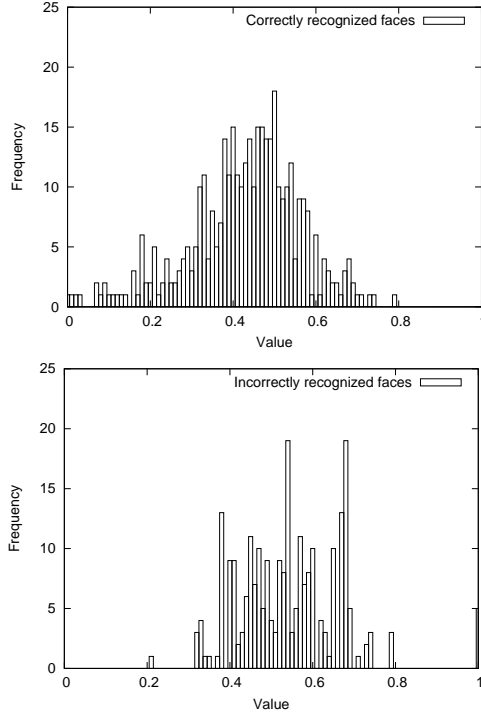


Figure 4: Histograms of the correctly (top) and incorrectly (bottom) classified faces using the *vector number* measure

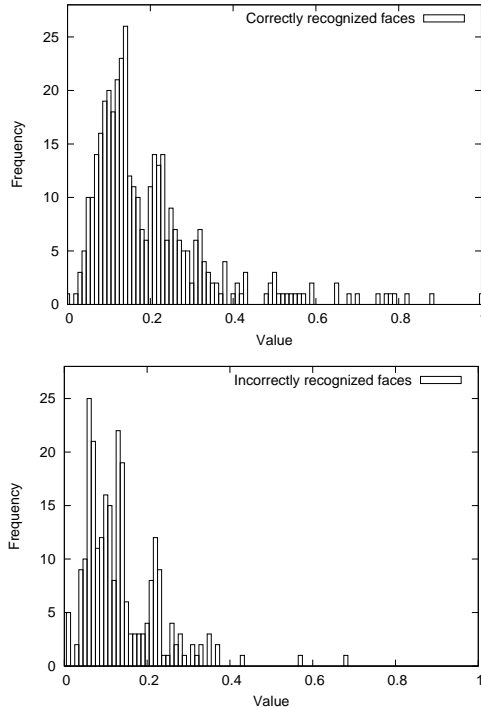


Figure 5: Histograms of the correctly (top) and incorrectly (bottom) classified faces using the *standard deviation* measure

To summarize:

- *relative confidence value (rel)* measure is the best proposed one;
- *absolute confidence value (abs)* method has also very good separation abilities;
- *vector number (vect)* measure can bring some complementary information for our task;
- contribution of the *standard deviation (sd)* measure is questionable and must be confirmed experimentally.

4.2.2 Accuracy of the separate measures

In the second experiment we would like to show the performance of the above described measures used separately without any combination. As in many other articles in the confidence measure field, we will use the Receiver Operating Characteristic (ROC) curve (Brown and Davis, 2006) for evaluation of this experiment. This curve clearly shows the relationship between the true positive and false positive rates for the different *acceptance* threshold.

Figure 6 shows the results of the separately used *absolute confidence value*, *relative confidence value*, *vector number* and *standard deviation* measures. This experiment shows that the *relative confidence value* method significantly outperforms the all other approaches.

We can further deduce that our assumption in the fourth proposed measure was not correct. Based on this experiment we can consider that the dependence between the value of the standard deviation and the correctly recognized faces is reversed. We modify the definition of such measure as follows: only the faces where $S > T$ are accepted.

After this modification we can conclude that all proposed measures are suitable for our task in order to identify incorrectly recognized faces. Note that the corrected version of the ROC curve of the fourth *standard deviation* measure is reported in this figure with the *modified sd* caption.

We will further compare the results of the separate measures with the whole composed approach. Therefore, we created the Table 1 to show the scores of the separate measures with optimal threshold configurations. The F-measure (F-mes) (Powers, 2011) is used as an evaluation metric, the Precision (Prec) and Recall (Rec) are also reported in this table. Note that the optimal threshold \hat{T} value has been defined for the “best” compromise between precision and recall values as follows:

$$\hat{T} = \arg \min_T \left| 1 - \frac{Prec}{Rec} \right| \quad (11)$$

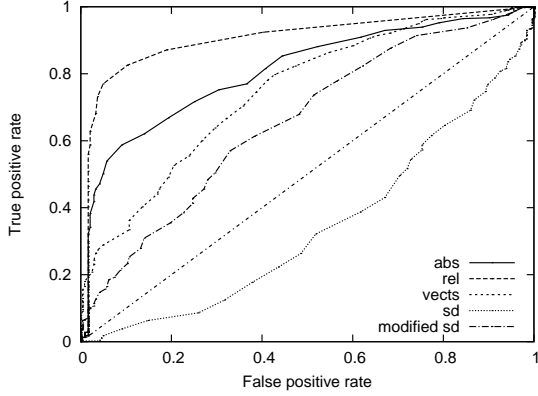


Figure 6: ROC curves of the four proposed measures used separately. The corrected *standard deviation* measure is reported with the *modified sd* label.

Table 1: Performance of the measures used separately [%]

Confidence Measure	Prec	Rec	F-mes
absolute confidence value	65.7	60.6	63.0
relative confidence value	69.6	60.8	64.9
vector number	62.2	63.5	62.8
standard deviation	58.9	60.3	59.6

4.2.3 Accuracy of the whole composed approach

In the last experiment, we will evaluate the results of the whole composed confidence measure method. First, we will show the impact of the use of an MLP classifier with the separate measures. Then, we compare and evaluate all possible combinations of the proposed measures in order to show the complementarities among them.

Several MLP configurations are tested. The best MLP topology uses three layers. The number of the input neurons corresponds to the number of measures to combine, 10 neurons are in the hidden layer and two outputs are used to identify the *correctly* and *incorrectly* recognized faces. This MLP topology was set empirically on a small development corpus which contains 120 examples (i.e. 120 confidence values).

The results of this experiment are reported in the Table 2. These results show that the separate measures used with an MLP have better F-measure values (except *sd* approach) than used in the unsupervised way. A successive addition of the measures improves progressively the F-measure value. When all measures are combined, the resulting F-measure is close to 100%. This figure also shows that all measures bring complementary relevant information and are thus useful to be integrated to the whole composed approach (i. e. the whole combined approach gives the best recognition score).

Table 2: Performance of all combinations of the measures by an MLP classifier [%]

Confidence Measure	Prec	Rec	F-mes
1. Separate measures			
abs. confidence value (abs)	92.5	64.8	76.2
rel. confidence value (rel)	96.2	80.4	87.6
vector number (vect)	55.4	84.9	67.0
standard deviation (sd)	54.0	65.3	59.1
2. Combinations of two measures			
abs, rel	97.2	83.5	89.8
abs, sd	70.4	55.8	62.2
abs, vect	95.8	75.8	84.6
rel, sd	95.8	84.3	89.7
rel, vect	97.7	85.6	91.2
sd, vect	67.6	90.6	77.4
3. Combinations of three measures			
abs, rel, sd	96.7	90.0	93.2
abs, rel, vect	97.2	93.7	95.4
abs, sd, vect	93.4	90.5	91.9
rel, sd, vect	94.8	94.8	94.8
4. Combination of all measures (the whole approach)			
abs, rel, sd, vect	100	99.5	99.8

5 CONCLUSIONS AND PERSPECTIVES

We proposed and evaluated a novel confidence measure approach in the automatic face recognition task. The proposed approach combines two measures based on the *posterior* probability and two ones based on the *predictor* features in a supervised way with an MLP. We experimentally showed that the proposed approach is very efficient, because it detects almost all erroneous examples. We further showed that it is possible to use all four proposed measures separately. However, every measure brings complementary information and it is thus beneficial to combine all measures in the composed approach. We decided that the proposed confidence measure will be integrated into our application for the ČTK.

To summarize, the main scientific contribution of this paper consists in:

1. proposing two novel measures based on the *predictor* features;
2. proposing a combined supervised confidence measure approach which combines the measures from two groups of methods; two ones based on the *posterior* class probability and the other two ones on the *predictor* features;
3. evaluation of the proposed method in the face recognition task on the real ČTK data.

The first perspective consists in proposing of semi-supervised confidence measures. In this approach, the CM model will be progressively adapted

according to the recognized data. We will further integrate other more suitable features into our model. Another perspective consists in the use of our confidence measure approach in the task of automatic creation of the face corpora.

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